## Info card

Inductive Kplus sensors
i This info card serves as a supplement to the main position sensors catalogue and to the individual data sheets. For further information and contact addresses please visit our homepage at www.ifm.com

## Intended use

While in use the products are exposed to influences which may have an effect on function, life, quality and reliability of the product.
It is the customer's responsibility to ensure that the products are suitable for the intended application. This applies in particular to applications in hazardous areas and with adverse environmental influence such as pressure, chemicals, temperature fluctuations, moisture and radiation as well as mechanical stress, especially if the products are not installed properly.
Using the products in applications where the safety of people depends on the function of the product is not permitted Non-compliance may result in death or serious injuries.

## Operating principle of an inductive Kplus sensor

Same sensing range on all metals (correction factor =1). A transmitting and receiving coil system on a PCB constitutes a transformer. Electrically conductive materials in the near field affect the coupling factor of the transformer
The change of the coupling factor is converted into a switched output. By not using a ferrite core, the inductive Kplus sensors are less sensitive to interference caused by strong magnetic fields.

(1) Connection
4) PCB with transmitting and receiving co
(2) Housing
(5) Alternating electromagnetic field = active zone
(3) Evaluation circuit
(6) Target = electrically conductive material

## Glossary of important terms

| Active zone | Area above the sensing face in which the sensor reacts to the approach of the target. |
| :---: | :---: |
| Output function | Normally open: Object within the active zone > output switched. |
|  | Normally closed: Object within the active zone > output blocked. |
|  | Positive switching: positive output signal (to L-). |
|  | Negative switching: negative output signal (to L+). |
| Rated insulation voltage | DC units with protection class II: 250 V DC units with protection class III: 60 V DC |
| Rated short-circuit current | For short-circuit-proof units: 100 A |
| Rated impulse withstand voltage | DC units with protection class II: 4 kV ( overvoltage category III) DC units with protection class III: 60 V DC: 0.8 kV (气 overvoltage category II) |
| Power-on delay time | The time the sensor needs to be ready for operation after application of the operating voltage (in the millisecond range). |
| Operating voltage | The voltage range in which the sensor functions safely. A stabilised and smoothed direct voltage should be used! Take into account residual ripple! |
| Utilisation category | DC units: DC-13 (control of solenoids) |


| Hysteresis | Difference between the switch-on and the switch-off point. |
| :---: | :---: |
| Short-circuit protection | ifm sensors are protected against excessive current by means of a pulsed short-circuit protection. The inrush current of incandescent lamps, electronic relays and low resistance loads may cause this protection to cut in and turn the sensor off! |
| Storage temperature | $-40^{\circ} \mathrm{C} . . .85^{\circ} \mathrm{C}$ acc. to EN $60068-2-1 \mathrm{Aa} / 2 \mathrm{Ba}$ : Duration of test 16 h each. Exception: For units specified with a lower or higher temperature, the data sheet value is taken as the guide value for the storage temperature. |
| Standard target | Square steel plate (e.g. S235JR) of a thickness of 1 mm with a side length (a) equal to the diameter of the sensing face or $3 \times \mathrm{S}_{\mathrm{n}}$, depending on which value is the highest. |
| Product standard | IEC 60947-5-2 |
| Repeatability | Difference between any two $\mathrm{Sr}_{\mathrm{r}}$ measurements. Max. $10 \%$ of $\mathrm{S}_{\mathrm{r}}$. |
| Switch point drift | Shift in the switch point owing to changes in the ambient temperature. |
| Switching frequency | Damping with standard target $(a \times a)$ at half $S_{n}$. The ratio damped to undamped $($ mark to space $)=1: 2$. |
| Protection | IPxy According to IEC 60529 <br> IP68 Test condition: 1 m water depth for 7 days <br> IP69k To ISO 20653 (replacement for DIN 40050-9) |
| SELV | Safety Extra Low Voltage (complies with protection class III). |
| Current consumption | Current for the internal supply of 3-wire DC units. |
| Degree of soiling | Inductive proximity sensors are designed for degree of soiling 3. |

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Sensing range (referred to the standard target)


Nominal sensing range $\mathrm{S}_{n}$
Real sensing range $\mathrm{S}_{\mathrm{r}}$
Useful sensing range $\mathrm{S}_{\mathrm{u}}$
Assured sensing range = operating distance S Safe switch-off distance
= characteristic value of the unit
$=$ individual deviation at room temperature between $90 \%$ and $110 \%$ of $S_{n}$
= switch point drift between $90 \%\left(\mathrm{~S}_{\mathrm{umin}}=\mathrm{S}_{\mathrm{a}}\right)$ and $110 \%\left(\mathrm{~S}_{\mathrm{umax}}\right)$ of Sr
$=$ reliably switched between $0 \%$ and $81 \%$ of $S_{n}$
$=\mathrm{S}_{\mathrm{umax}}+$ max. hysteresis $=143 \%$ of $\mathrm{S}_{\mathrm{n}}$

## Influence of the target size

## Tips on flush and non-flush mounting in meta

Installation instructions cylindrical designs


|  |  | $\mathrm{S}_{\mathrm{n}}$ | a | b | c | d | e | f | g | h |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| M8 | b | 1,5 | - | - | 7 | - | - | 16 |  | $8 x S_{n}$ |
|  |  | 3 | - | - | 7 | - | - | 16 |  |  |
|  | nb | 4 | 8 | 8 | 12 | 8 | 32 | - | 32 |  |
|  |  | 6 | 8 | 12 | 12 | 12 | 32 | - | 32 |  |
| M12 | b | 3 | - | - | 8 | - | - | 24 | - |  |
|  |  | 4 | - | - | 8 | - | - | 24 | - |  |
|  | nb | 8 | 10 | 10 | 18 | 16 | 36 | - | 48 |  |
|  |  | 10 | 12 | 20 | 18 | 20 | 48 | - | 48 |  |
| M18 | b | 5 | - | - | 11 | - | - | 36 | - |  |
|  |  | 8 | - | - | 11 | - | - | 36 | - |  |
|  | nb | 12 | 15 | 15 | 27 | 24 | 54 | - | 72 |  |
|  |  | 15 | 18 | 30 | 27 | 30 | 72 | - | 72 |  |
| M30 | b | 10 | - | - | 17 | - | - | 60 | - |  |
|  |  | 15 | - | - | 17 | - | - | 60 | - |  |
|  | nb | 22 | 22,5 | 22,5 | 45 | 37 | 90 | - | 150 |  |
|  |  | 30 | 30 | 37 | 45 | 37 | 150 | - | 150 |  |

$(1$ Installation instructions rectangular designs $\rightarrow$ see enclosed operating instructions or www.ifm.com
(1) Distance to the background
(2) Recommended target distance
(3) Recommended degree of coverage of the sensing face
(4) Recommended target size

Recommended detection conditions


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## Electrical connection

(1) Negative switching
(2) Positive switching
(3) Sensor 1
(4) Sensor $n$

## Connection systems



3-wire technology (negative or positive switching)


4-wire technology (positive switching, normally closed and normally open)

Series connection (AND)


Series connection of 3-wire units
Max. 4 units. Power-on delay times, voltage drops and current consumption add up. $\mathrm{U}_{\mathrm{B} \text { min }}$ (sensor) and $\mathrm{U}_{\text {HIGH min }}$ (load) must remain unchanged

Parallel connection (OR)


## Parallel connection 3-wire units

he current consumption of all non-switched units adds up. The units can be used in combination with mechan cal switches.

## Configuration of cables and

 connectorsColours: BK: black, BN brown, BU: blue, WH: white
Standard configuration for 3-wire DC:

|  |  | Cable | US-100 plug |
| :---: | :---: | :---: | :---: |
| $\mathrm{L}+$ |  | BN | Pin 1/BN |
| $\mathrm{L}-$ |  | BU | Pin 3/BU |
| Output | -L | BK | Pin 2 / WH <br> Pin $4 / \mathrm{BK}$ |

## Pin configuration of the US-100 connectors (view onto the plug

 at the unit)$$
\begin{aligned}
& \text { Pin 4: BK } \\
& \text { Pin 1: } \mathrm{BN}
\end{aligned}=\begin{aligned}
& \text { Pin 3: } \mathrm{BU} \\
& \text { Pin 2:WH }
\end{aligned}
$$

Please refer to the wiring diagrams in our main catalogue for position sensors for the cable and the pin configuration as well as the unit data of special versions.

## Magnetic flux density depending on distance and curren


(1) live wire
(2) sensor
(3) distance

